Seamless Power Management on IoT Devices — Lessons from an HVAC Use Case using RIOT

Jürgen Fitschen - SSV Software Systems GmbH

Slides available at:

https://ssv-embedded.github.io/RIOTSummit2020/

Who am I?

Jürgen Fitschen (jue89 on GitHub)
Systems Engineer at SSV Software Systems, Germany
Using RIOT since 2018

What we'll cover ...

Why does good power management *matter*?

How does it *work*?

It's all about *timers*!



Why does Good Power Management *Matter* to us?

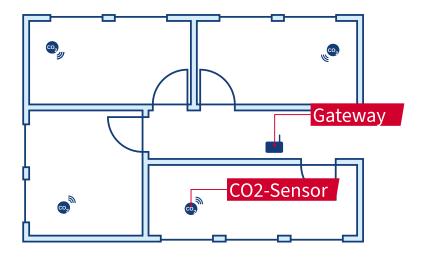


Retrofit Systems are our Passion.

- Goal: enhance efficiency and value of existing systems and environments
- Sensors and actuators must be deployed within already existing systems
- Some retrofit systems require 100+ sensors
 - **⇒** Battery-powered sensors and actuators are required!



Example Retrofit Setup: Battery-powered Sensors



- Task: Send notifications when the windows should be opened
- Measure CO₂ contentration in every room
- Send the sensor reading to gateway
- Notify occupier upon high sensor readings via e-mail



The CO₂ Sensor's Application Sequence



Phase	Duration	Current	Charge	Battery Charge: [1]	2,400 mAh = 8,640,000 mC
Measure	100 ms	1,000 µA	0.1 mC	Battery Self-discharge Current: [2]	1.9 μΑ
TX	50 ms	13,500 µA	0.7 mC	Number of Cycles:	1,444,454
RX	200 ms	8,200 μA	1.6 mC	Livetime:	13.74 years
Sleep	299,650 ms	10 μΑ	3.0 mC		

⇒ Reduce power consumption during sleep phase!

5.4 mC



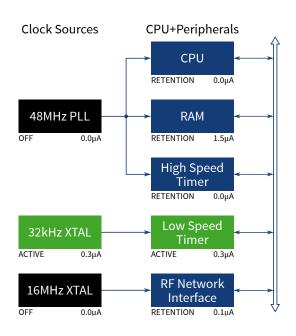
Sum:

300,000 ms

How does Power Management Work?



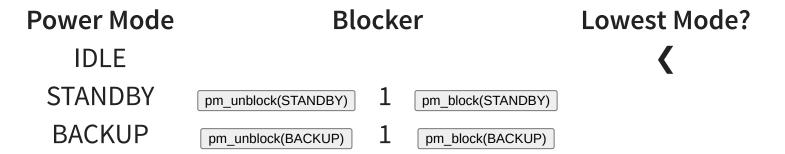
The Internals of the Microcontroller SAM R30^[3]





⇒ Set the *SLEEPCFG* register to "STANDBY" and the *RF Network Interface* to "SLEEP" during sleep phase!

RIOT has a Driver for Power Management



- pm_layered keeps track of which power mode can be entered
- The idle thread enters the lowest mode
- Someone must tell pm_layered which modes are allowed

→ For a seamless user experience, drivers must interact with pm_layered



It's all about *Timers*!



RIOT's Current Default Timer System: xtimer

```
#include "xtimer.h"
#include "timex.h"

static void callback (void * arg) {
    puts((char*) arg);

}

int main (void) {

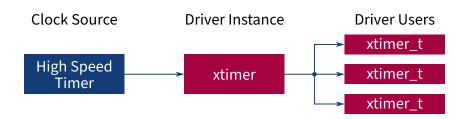
/* 1. Run a callback after 3s */

static xtimer_t cb_timer = {.callback = callback, .arg = "Hello World"};

xtimer_set(&cb_timer, 3 * US_PER_SEC);

/* 2. Sleep the current thread for 60s */
xtimer_sleep(60);

/* xtimer_sleep(60);
```



- ⇒ xtimer requires the High Speed Timer to run all the time
 - **⇒** STANDBY mode must not be entered at any time



There's an Alternative for the Rescue: ztimer

App's Makefile:

```
USEMODULE += ztimer ztimer_usec ztimer_msec ztimer_periph_rtt
USEMODULE += pm_layered

samr30-based-board/include/board.h:

# Make ZTIMER_USEC block/unblock STANDBY mode
#define CONFIG_ZTIMER_USEC_REQUIRED_PM_MODE PM_SLEEPCFG_SLEEPMODE
# Only block BACKUP mode on startup
#define PM_BLOCKER_INITIAL 0x0001
```

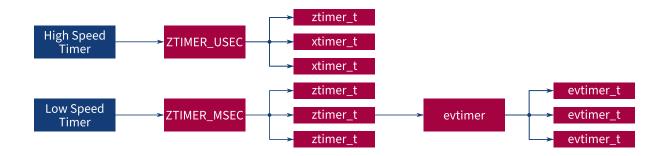
⇒ ztimer unblocks STANDBY mode if no ztimer_t requires ZTIMER_USEC to run



xtimer & ztimer can be Friends and Coexist!

⇒ xtimer_on_ztimer blocks STANDBY mode all the time

USEMODULE += ztimer_timer_usec ztimer_msec ztimer_periph_rtt ztimer_xtimer_compat evtimer evtimer_on_ztimer # evtimer_on_ztimer hasn't been merged, yet. See Pull Request #13661



⇒ ztimer_xtimer_compat doesn't implement xtimer_*64() methods

⇒ ztimer is utilized in our use case!



RIOT & Power Management: Status Quo?



Conclusion

RIOT has all important parts for PM inside ...

... but by default they aren't configured for reasonable power saving.

RIOT has three different timer systems ...

... but the *RIOT Developer Memo* could lead to one standard system. (cf. #12970)

RIOT is heading in the right direction for seamless power management!



References

- 1. Tadiran Batteries GmbH Datasheet: SL-860
- 2. Dittrich, Menachem, Yamin, Adamas Lithiumbatterien für Funksensornetzwerke
- 3. Microchip Technology Inc. SAM R30 Microcontroller

